



# **Smallsat technology trends and their impact on the future of solar system exploration**

Tony Freeman, JPL

Sept 2017

Jet Propulsion Laboratory, California  
Institute of Technology

3<sup>rd</sup> COSPAR Symposium 2017, Jeju, S. Korea

# Cubesats were 'toys' 18 years ago...





Disneyland, Anaheim, CA

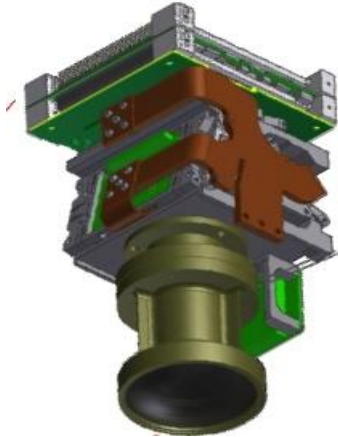


<https://www.planet.com/gallery/disneyland-parking-lot/>



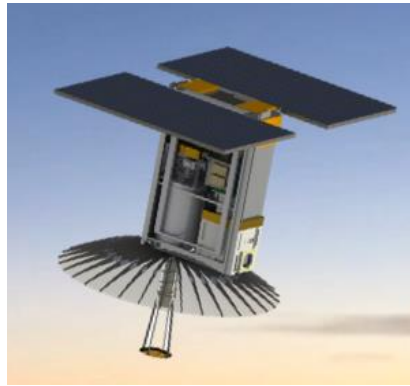
# Science Instrument Examples (1U = 1 liter)

HARP Imaging Polarimeter(3U)



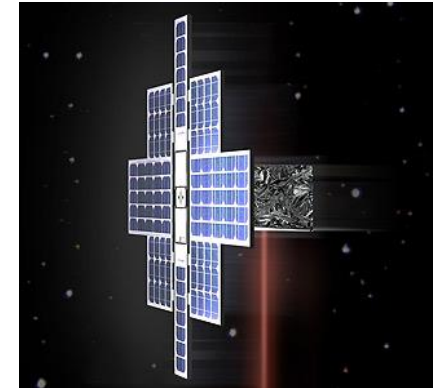
UMBC/SDL (2017)

RainCube radar (6U)



JPL (2017)

Lunar Flashlight (6U)  
NIR laser



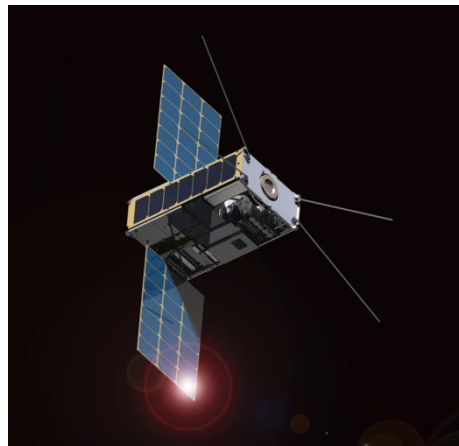
MSFC/JPL (2017)

Mass Spectrometer (3U)



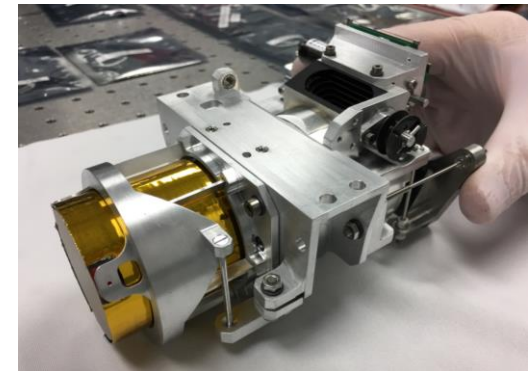
JPL (TBD)

LunarIceCube (6U)  
IR spectrometer



GSFC (2018)

VSWIR-Dyson (2U)  
spectrometer



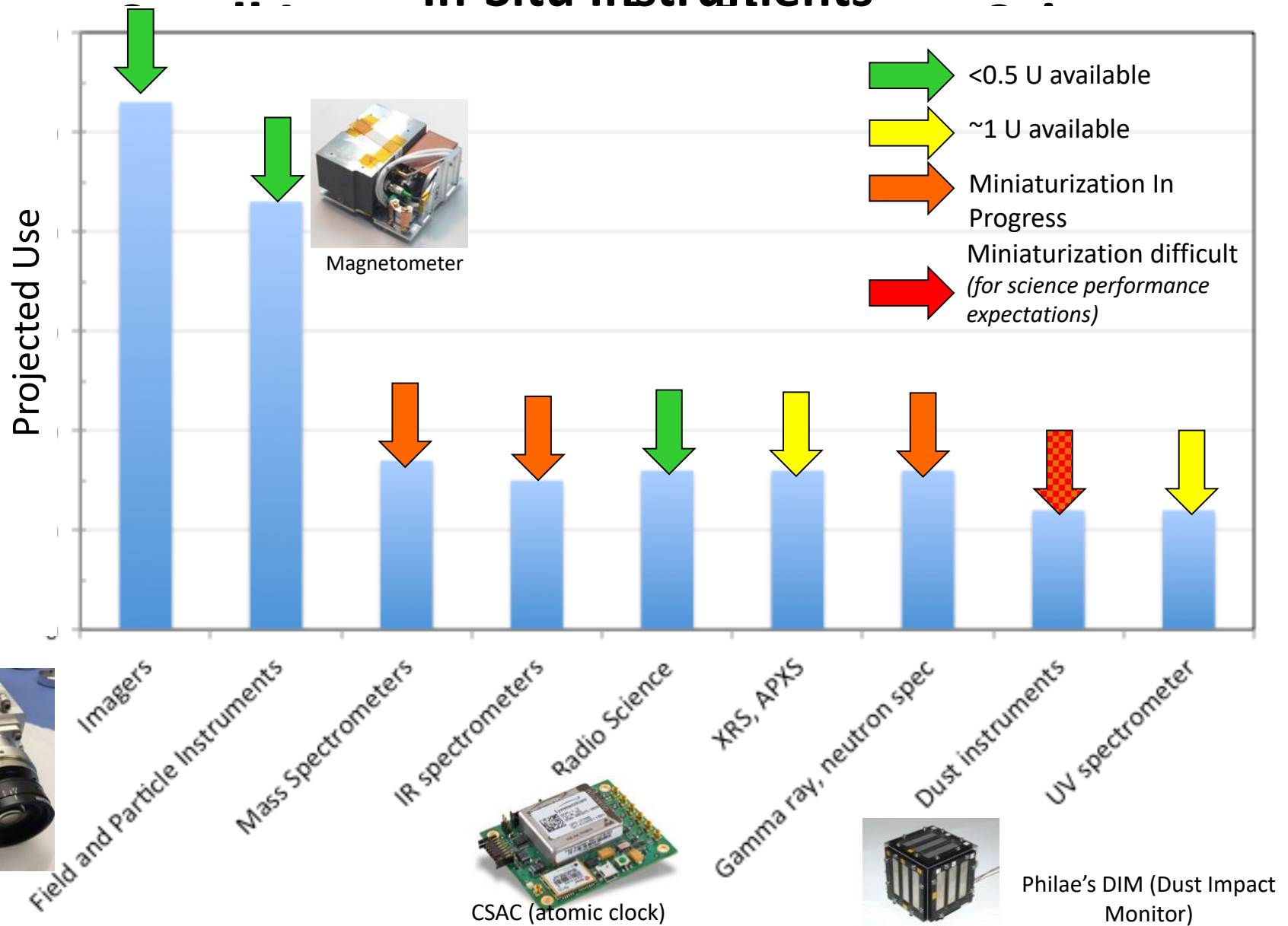
JPL (TBD)

# Cubesat-sized Instruments – 2012 and 2017

Technology	Selva* and Krejci, 2012	Freeman 2017	Justification
Atmospheric Chemistry Instruments	Problematic	Feasible	PICASSO, IR sounders
Atmos Temp and Humidity Sounders	Feasible	Feasible	
Cloud Profile and rain radars	Infeasible	Feasible	JPL RainCube Demo
Earth Radiation Budget radiometers	Feasible	Feasible	SERB, RAVAN
Gravity Instruments	Feasible	Feasible	Need a demo mission
Hi-res Optical Imagers	Infeasible	Feasible	Planetlabs
Imaging microwave radars	Infeasible	Feasible	Ka-Band 12U design
Imaging multi-spectral radiometers (Vis/IR)	Problematic	Feasible	AstroDigital
Imaging multi-spectral radiometers ( $\mu$ Wave)	Problematic	Feasible	TEMPEST,
Lidars	Infeasible	Feasible	DIAL laser occultation
Lightning Imagers	Feasible	Feasible	
Magnetic Fields	Feasible	Feasible	InSPIRE
Multiple direction/polarization radiometers	Problematic	Feasible	HARP Polarimeter
Ocean color instruments	Feasible	Feasible	SeaHawk
Precision orbit	Feasible	Feasible	CanX-4 and -5
Radar altimeters	Infeasible	Feasible	Bistatic LEO-GEO
Scatterometers	Infeasible	Feasible	GPS refl. (CyGNSS)

\*Selva and Krejci, A survey and assessment of the capabilities of Cubesats for Earth observation, Acta Astronautica, 74, 50–68 (2012)

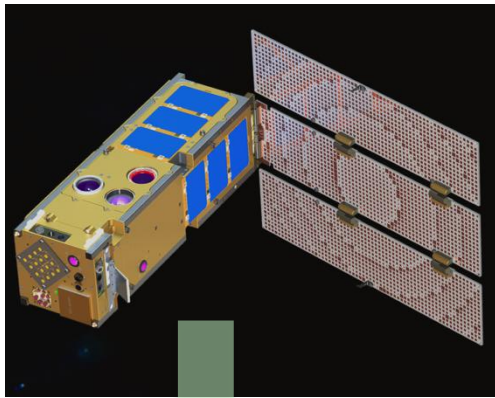
# In-Situ Instruments



## RF

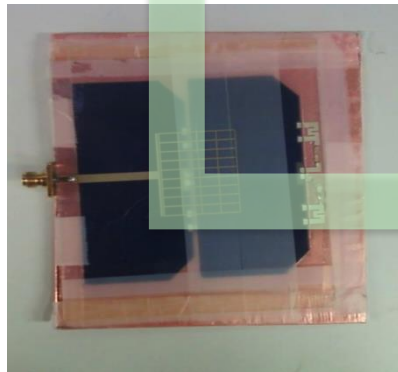
ISARA

Reflectarray/Solar Array



JPL (2017)

Optically Transparent/  
RF Reflective Coatings

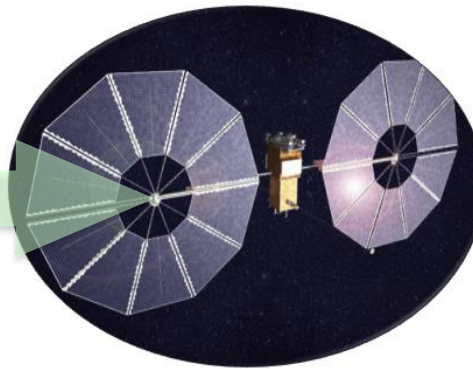


Utah State (TBD)

# Telecom

- RF Reflectarrays can scale to larger antennas
- Active and passive Optical Comm
- Optically transparent/RF reflective coatings printed on large solar arrays on deep space missions

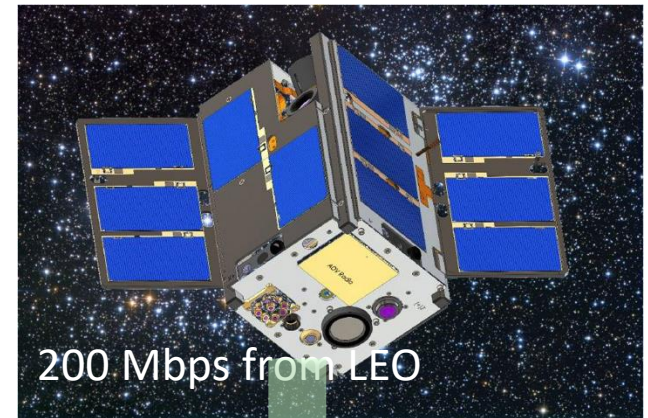
Dual-use Solar arrays



(TBD)

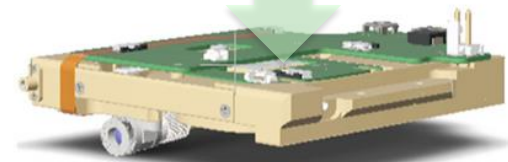
## Optical

Cubesat Optical Comm Demo



Aerospace (2016/7)

Bridgesat Optical Comm Terminal



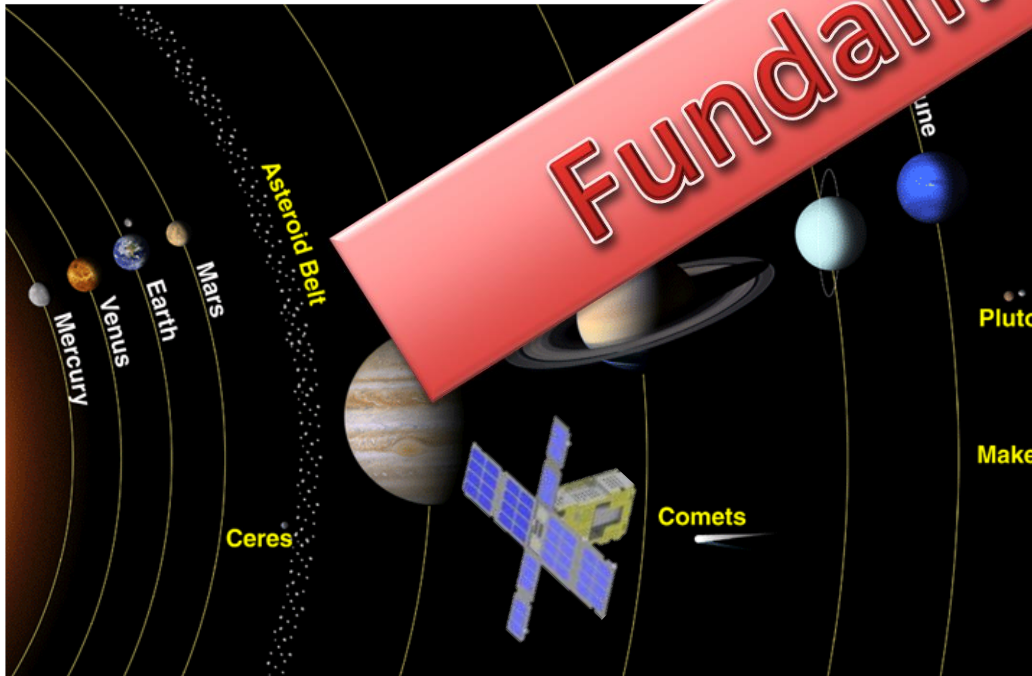
Bridgesat (TBD)



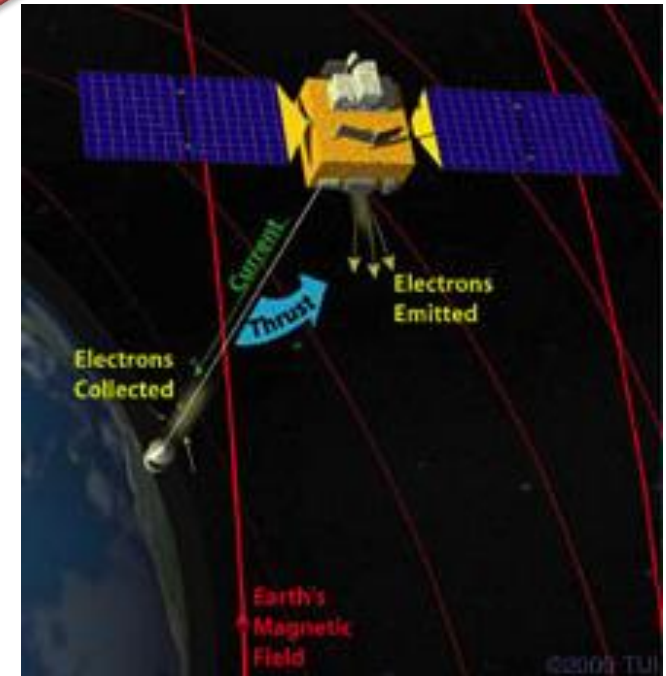
# Power Systems

- Solar Array Plateau ~ 45% efficiency?
- Batteries that work over wide temperature ranges?
- Electromagnetic tethers – great if there's a magnetic field?
- Progress in nuclear dependent on NASA/JPL, Compact RTGs?

Solar power distance limit?



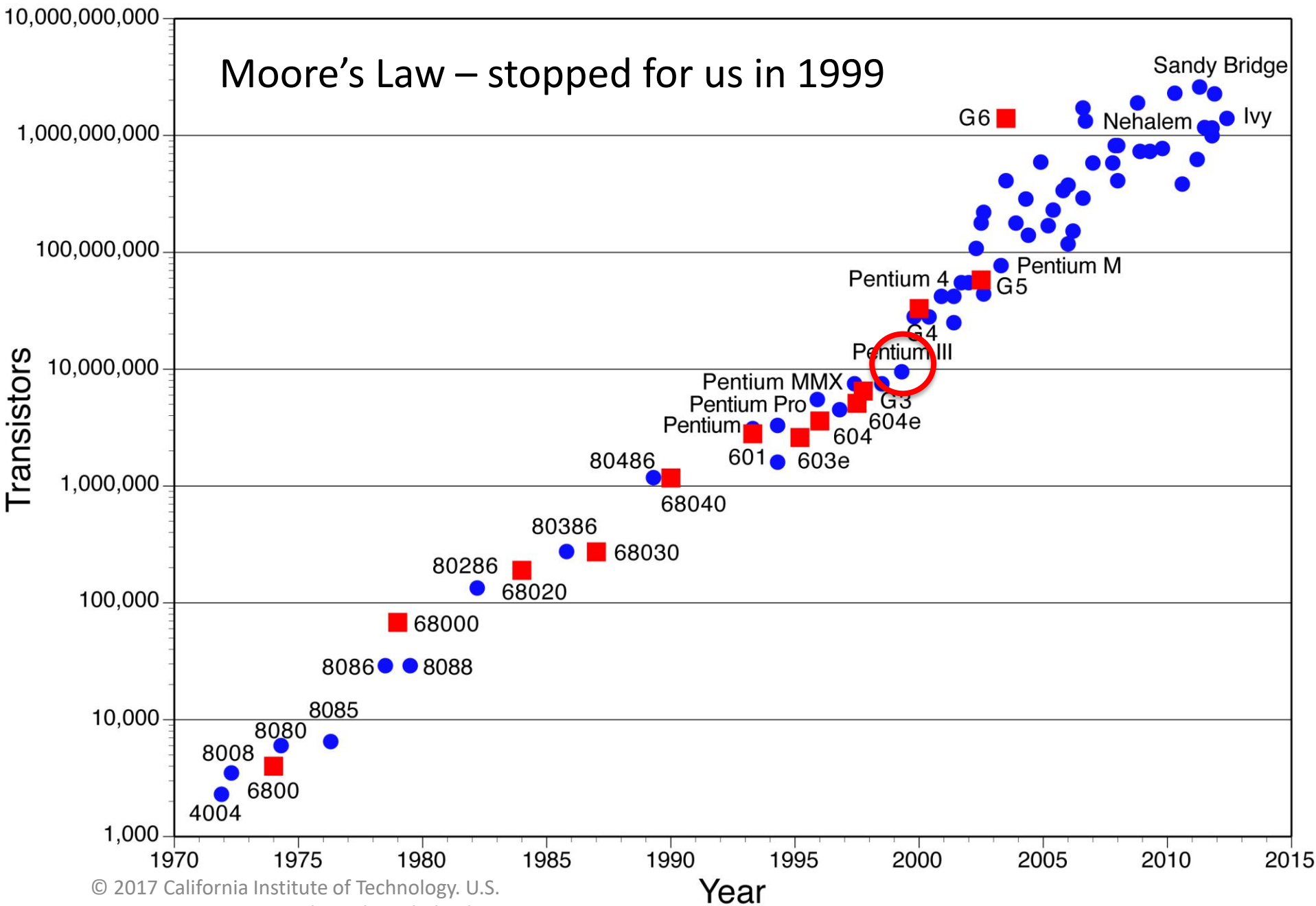
Electromagnetic Tethers



Tethers Unlimited (TBD)

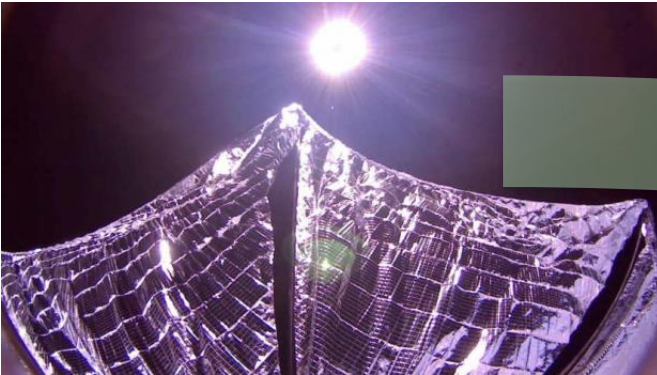


# Spacecraft S/W Functions



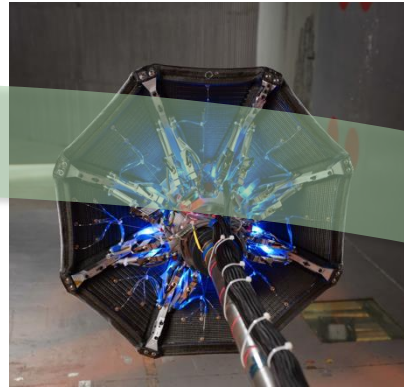
# Propulsion

Solar Sail (first design in 1976)



Planetary Society (2015)

Deployable Aeroshell



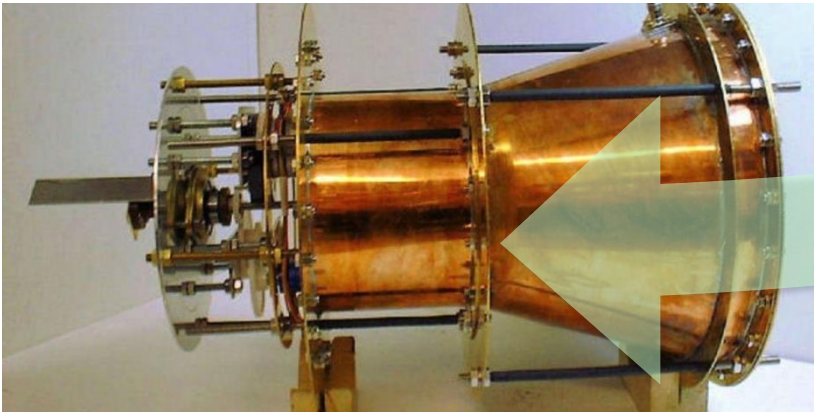
NASA Ames (2017)

MicroSpray  
Electric propulsion



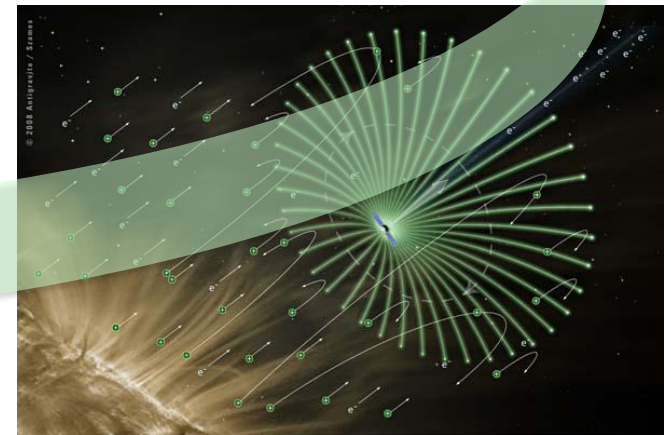
Busek (2019)

NASA EM Drive



NASA JSC (???)

eSail demo

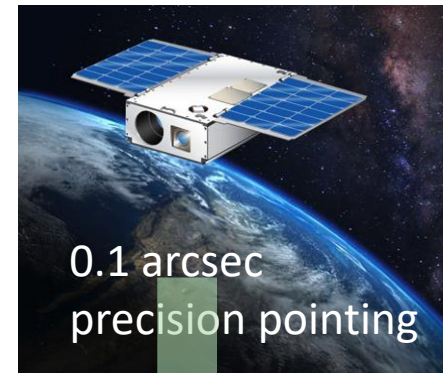


Aalto U. Finland (2017)

# Attitude Determination and Control

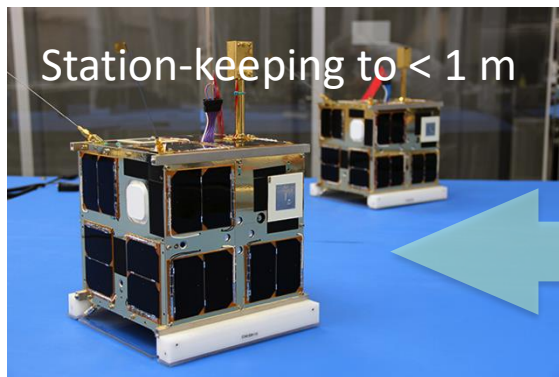
- Fraction of an arcsec pointing
- Navigation using Pulsars
- Precision Formation Flying

Asteria  
Exoplanet Hunter



JPL/MIT (2018)

CanX-4 and -5  
Precision Formation Flying



UTIAS SFL (2014)

XPNav-1  
Deep Space navigation using X-ray Pulsars



China (2016)



# Cubesat Assembly

(in less than one workday)



Video clip courtesy Tyvak Corporation

# Advanced Manufacturing

- 3-D printed valves on Falcon-9
- 3-D printing of S/C components
- Multi-function Structures
- Robot-assisted Integration and Test
- S/C build cycles < 1 week

3D Printed Spacecraft



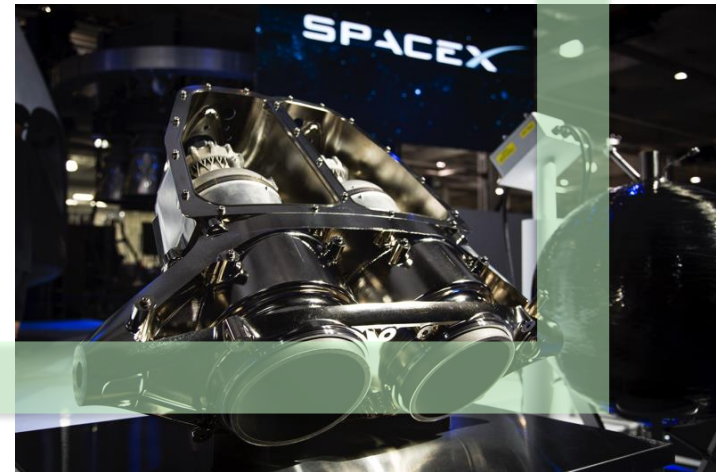
Planetary Resources (2014)

Robot-assisted assembly  
[15 Smallsat S/C per week]



OneWeb (2018)

3-D Printed Rocket Engine

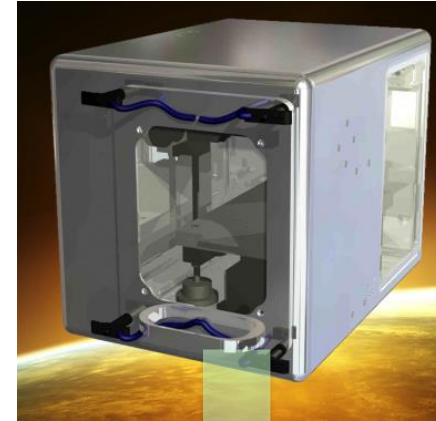


Space-X (2014)

# Additive Manufacturing

- 3-D printer as a flight payload
- Print Hardware Upgrades
- Use In situ resources
- Large-scale Structures in Space

First 3-D Printer in Space



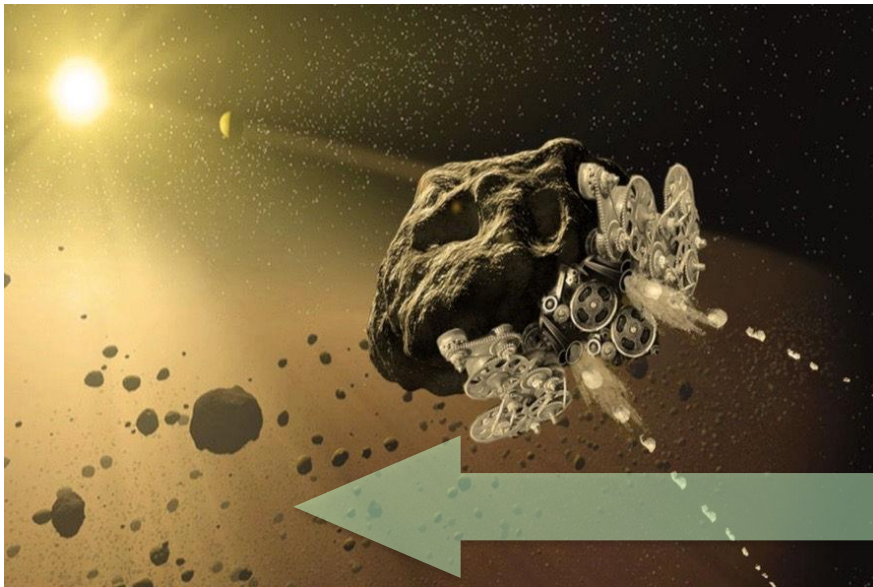
Made In Space on ISS (2014)

Object printed from asteroid metals



Planetary Resources (2016)

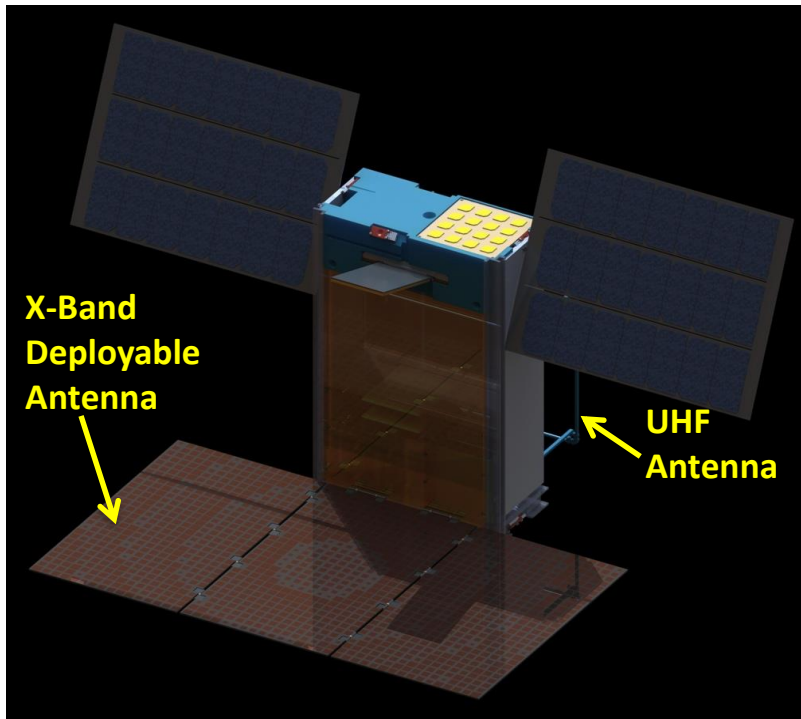
Making a Spacecraft out of an Asteroid



Made In Space (TBD)



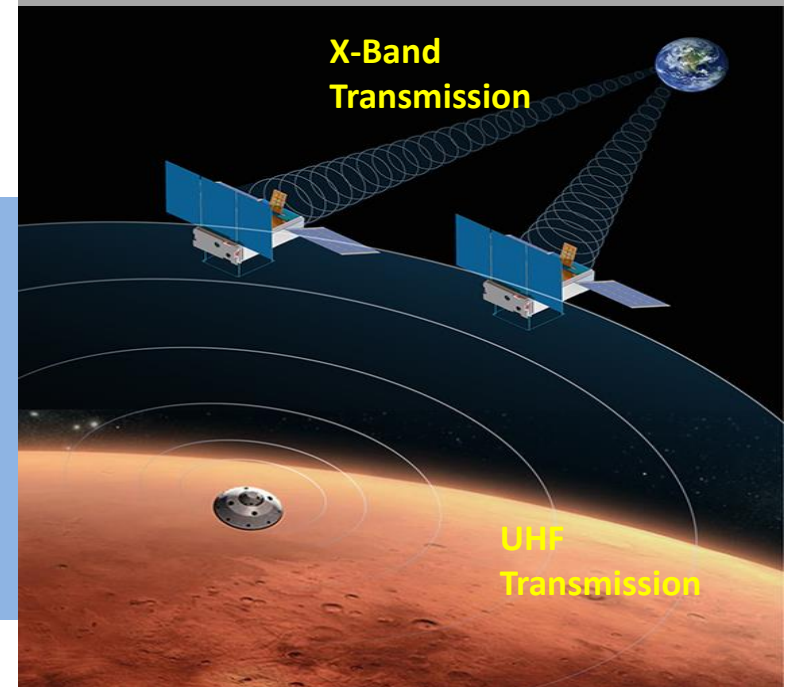
# Mars Cube One



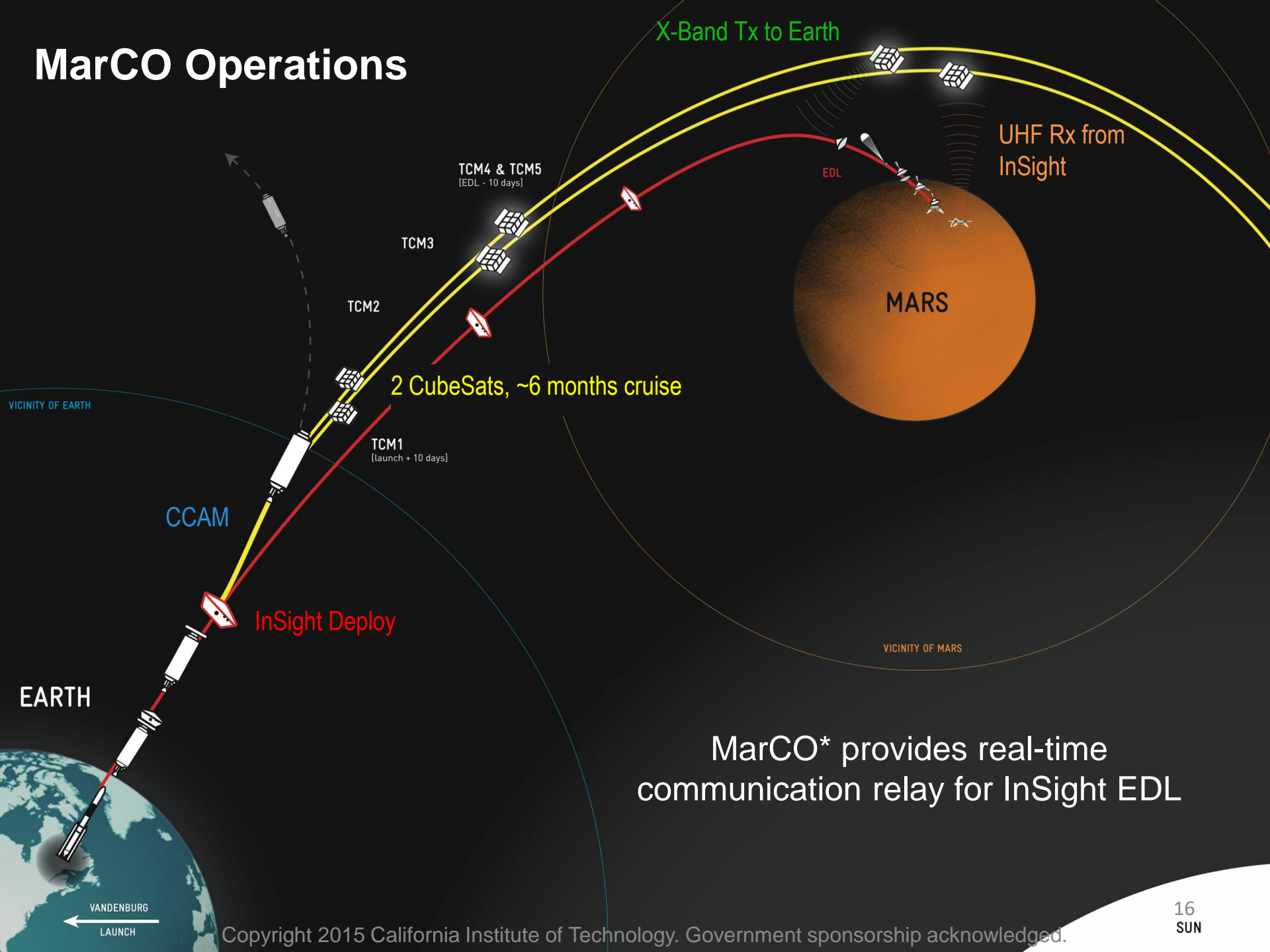
- Two redundant 6U CubeSat spacecraft
- Launch: Mar. 2016; Arrival: Sep. 2016
- Real-time relay of InSight EDL data
  - UHF link: InSight lander to MarCO
  - X-band link: MarCO to Earth

**A Technology Demonstration of communications relay system for Mars missions' critical events such as the 2016 InSight entry, descent, & landing.**

*Interplanetary Travel  
Flyby Mars*



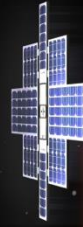
# MarCO Operations



MarCO\* provides real-time communication relay for InSight EDL

COSPAR 2017

LUNAR

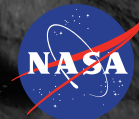


Lunar Flashlight—  
shining a light into  
the dark corners of  
our Moon

FLASHLIGHT

[SLS flight EM-1  
plans to carry up to  
12 cubesats into  
lunar space in 2018]

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# NEAScout

Near Earth Asteroid ScoutSat  
(NEAScout)

## Close Proximity Science

High-resolution imaging,

10 /px GSD over >30% surface

**SKGs: Local morphology Regolith properties**



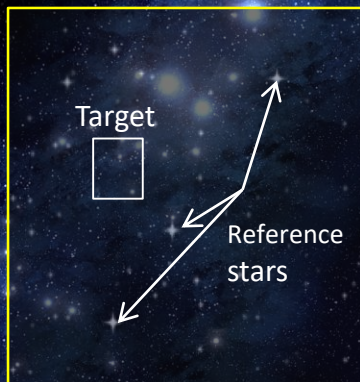
**JPL IntelliCam**  
(Updated OCO-3  
Context Camera)

## NEA Reconnaissance

<100 km distance at encounter

50 cm/px resolution over 80% surface

**SKGs: volume, global shape, spin properties, local environment**



## Target Detection and Approach:

50K km, Light source observation

**SKGs: Ephemeris determination and composition assessment (color)**

Courtesy: J. Castillo-Rogez, JPL



# EXPLORATION MISSION-1: LAUNCHING SCIENCE & TECHNOLOGY SECONDARY PAYLOADS



## PRIMARY MISSION

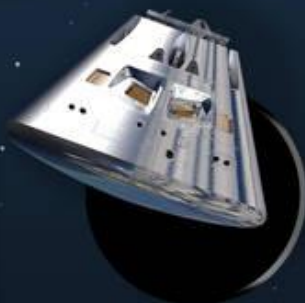
TESTING SLS  
AND ORION

## SPACE LAUNCH SYSTEM (SLS)

LIFTS MORE  
THAN ANY  
EXISTING  
LAUNCH  
VEHICLE

## ORION STAGE ADAPTER

SUPPORTS BOTH  
PRIMARY MISSION  
AND SECONDARY  
PAYLOADS



## ORION SPACECRAFT

TRAVELING THOUSANDS OF  
MILES BEYOND THE MOON,  
WHERE NO CREW VEHICLE  
HAS GONE BEFORE



## SECONDARY PAYLOADS

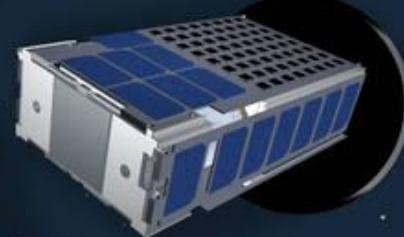
THE RING THAT WILL  
CONNECT THE ORION  
SPACECRAFT TO NASA'S  
SLS ALSO HAS ROOM  
FOR 13 HITCHHIKER  
PAYLOADS

## AVIONICS

(SELF-CONTAINED AND INDEPENDENT  
FROM THE PRIMARY MISSION)  
SEND CUBESATS ON THEIR WAY

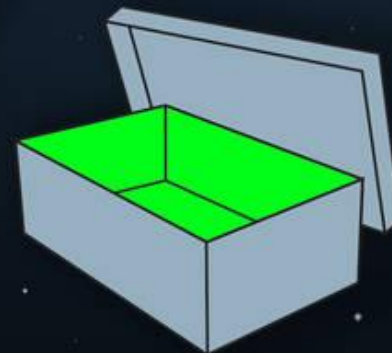
## 13 CUBESAT EXPLORERS

GOING TO DEEP SPACE  
WHERE FEW CUBESATS  
HAVE EVER GONE  
BEFORE.



## SHOEBOX SIZE

PAYLOADS EXPAND  
OUR KNOWLEDGE  
FOR THE JOURNEY  
TO MARS

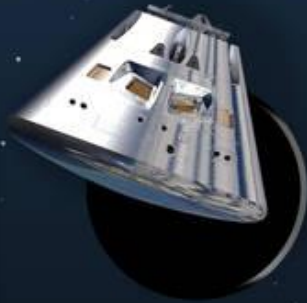


#RideOnSLS

# EM-1 (2018): THE FIRST SCIENCE SWARM OF CUBESATS [Ride-alongs]

**1**  
**PRIMARY MISSION**  
TESTING SLS  
AND ORION  
**SPACE  
LAUNCH  
SYSTEM  
(SLS)**  
LIFTS MORE  
THAN ANY  
EXISTING  
LAUNCH  
VEHICLE

**ORION  
STAGE  
ADAPTER**  
SUPPORTS BOTH  
PRIMARY MISSION  
AND SECONDARY  
PAYLOADS



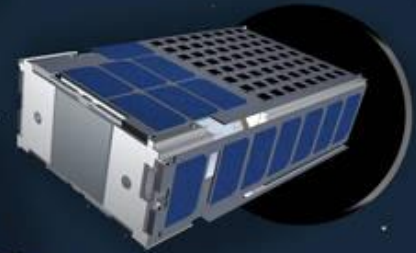
**ORION  
SPACECRAFT**  
TRAVELING THOUSANDS OF  
MILES BEYOND THE MOON,  
WHERE NO CREW VEHICLE  
HAS GONE BEFORE



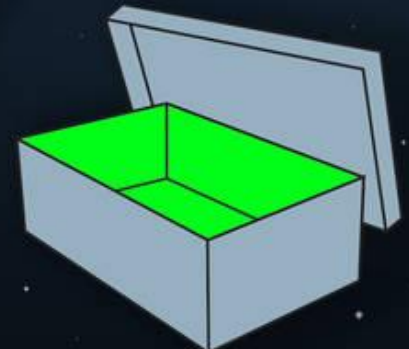
**2**  
**SECONDARY  
PAYLOADS**  
THE RING THAT WILL  
CONNECT THE ORION  
SPACECRAFT TO NASA'S  
SLS ALSO HAS ROOM  
FOR 13 HITCHHIKER  
PAYLOADS

**AVIONICS**  
(SELF-CONTAINED AND INDEPENDENT  
FROM THE PRIMARY MISSION)  
SEND CUBESATS ON THEIR WAY

**13**  
**CUBESAT  
EXPLORERS**  
GOING TO DEEP SPACE  
WHERE FEW CUBESATS  
HAVE EVER GONE  
BEFORE.



**SHOEBOX SIZE**  
PAYLOADS EXPAND  
OUR KNOWLEDGE  
FOR THE JOURNEY  
TO MARS



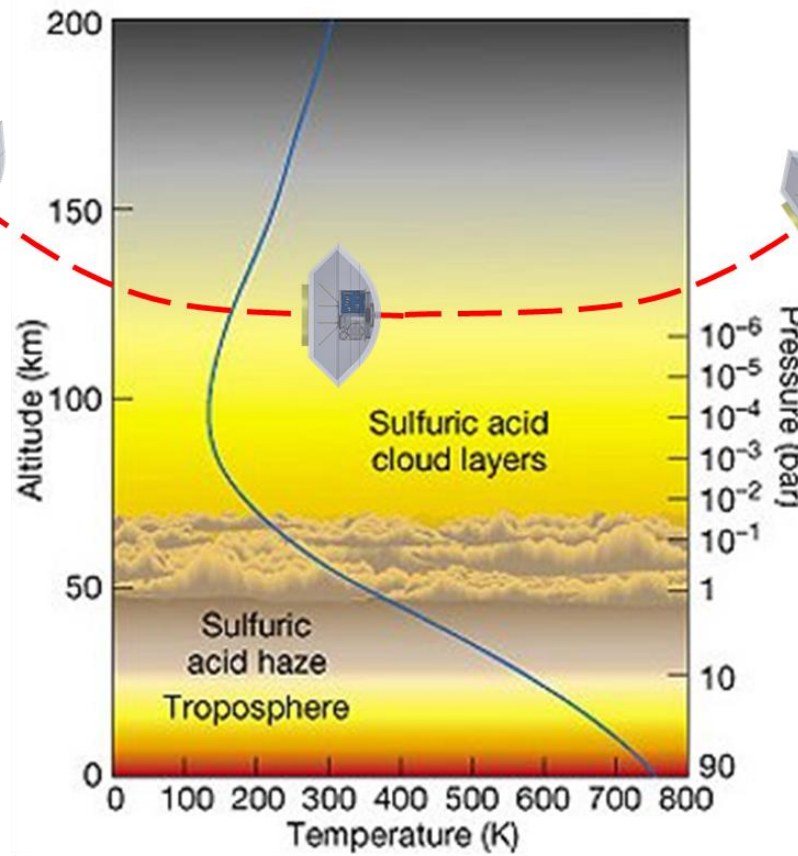
**#RIDEOnSLS**



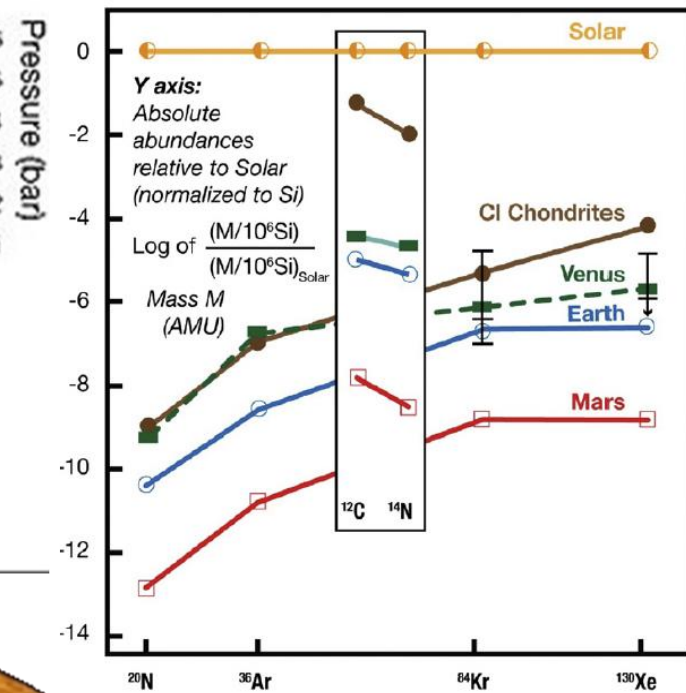
# Cupid's Arrow (Venus) Mission Concept

## Atmospheric Entry Conditions

Probe dips  
down to  
120km



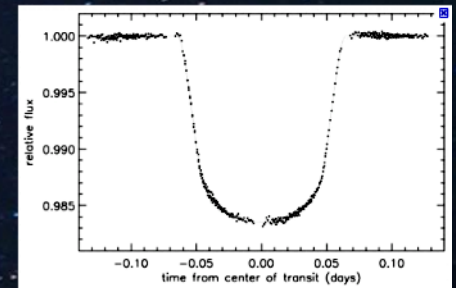
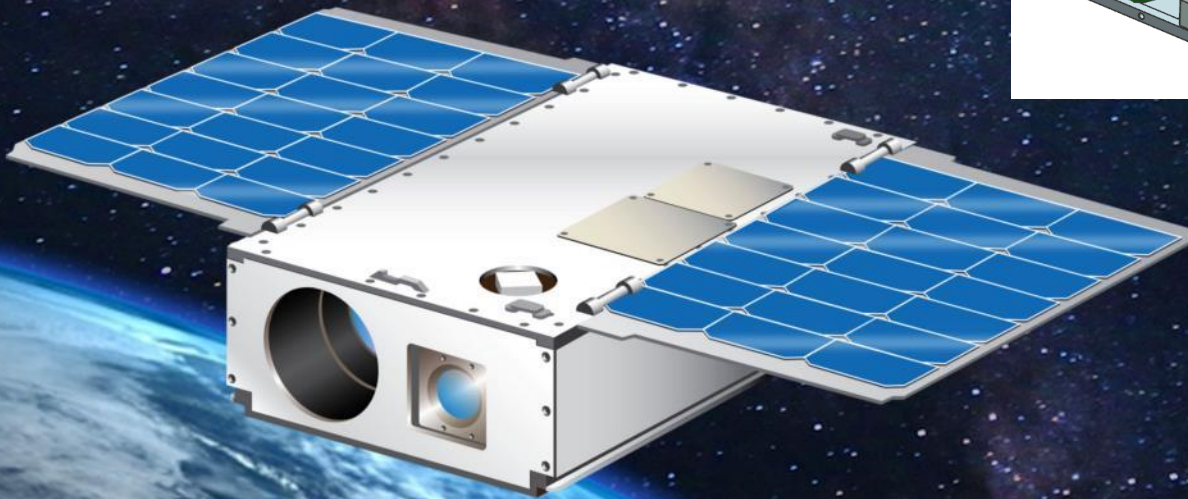
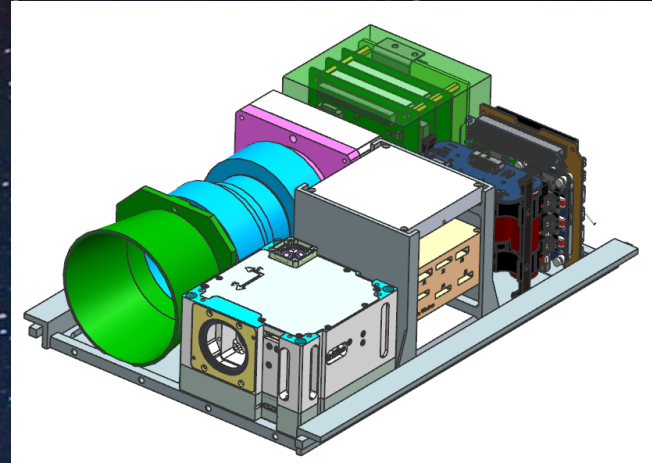
- Recent DS<sup>3</sup> award of NASA funding to mature this mission concept
- PI: Christophe Sotin, JPL



Pepin et al., 1991; Chassefiere et al., 2012)

# ***ASTERIA: Arcsecond Space Telescope Enabling Research in Astrophysics***

- PI: Sara Seager, MIT
- Single star at-a-time planetary transits
- 0.1 arcsec precision pointing

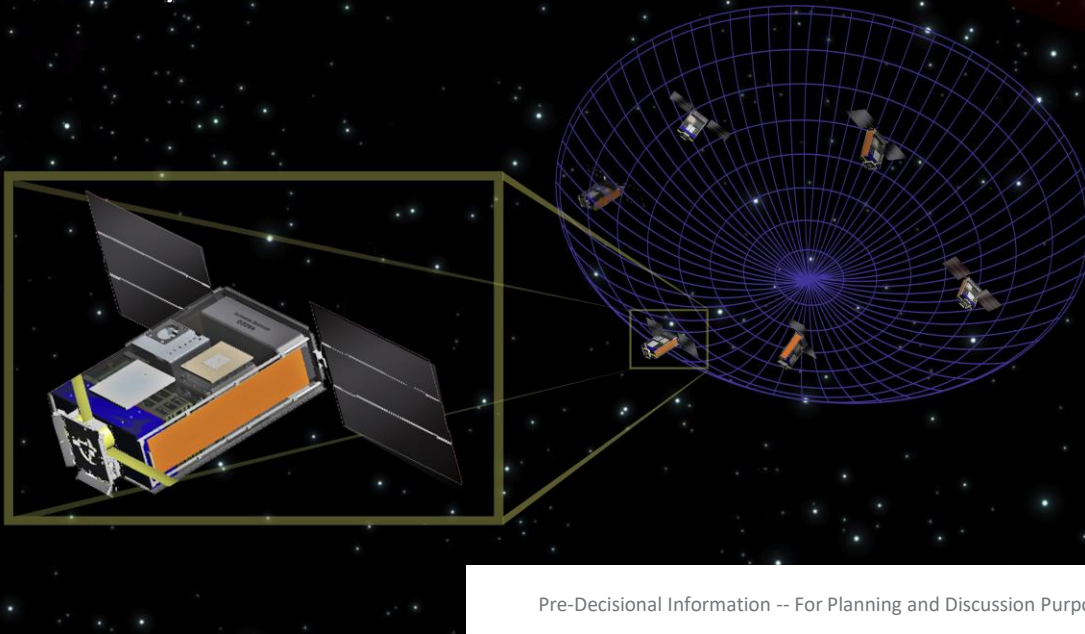
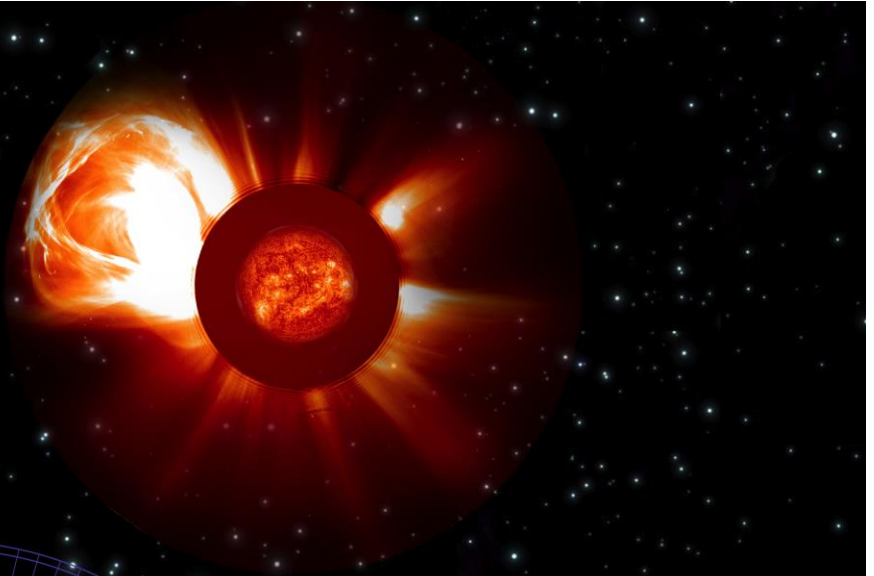




# Sun Radio Imaging Space Experiment

SMEX Heliophysics Step II selection - Mission Concept

- PI: Justin Kasper, U of MI
- PS: Joe Lazio (9X)
- Use radio emission to track CME particle acceleration and transport
- 6 spacecraft synthetic aperture
- D33 payload (GPS + HF rcvr)
- SDL S/C and I&T



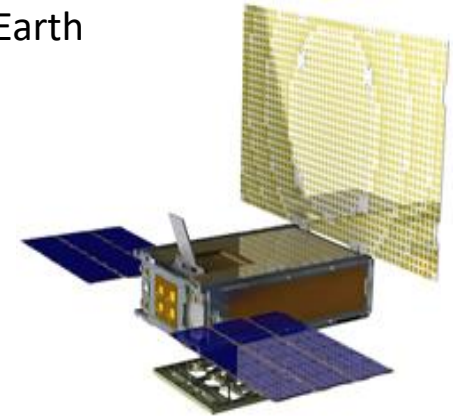


# CubeSats at Saturn?

- Power
  - 1.2-2W solar power @ Saturn
    - ~ 11 days to fully charge 200 Whr capacity with 1.2 W array
  - Up to 1200 Whr with primary batteries
- Control
  - $<0.003^\circ$  pointing;  $>35^\circ/\text{sec}$  slew rates
- Communications (relay to primary)
  - X band with 5 W RF power
  - Antennas  $> 28$  dBi gain X band
- Propulsion (chemical)
  - $\sim 250$  m/s  $\Delta V$  for a 12 kg 6U
- Thermal
  - Some concepts would benefit from a compact RHU to survive thermal extremes



Lunar IceCube: 120 W @ Earth



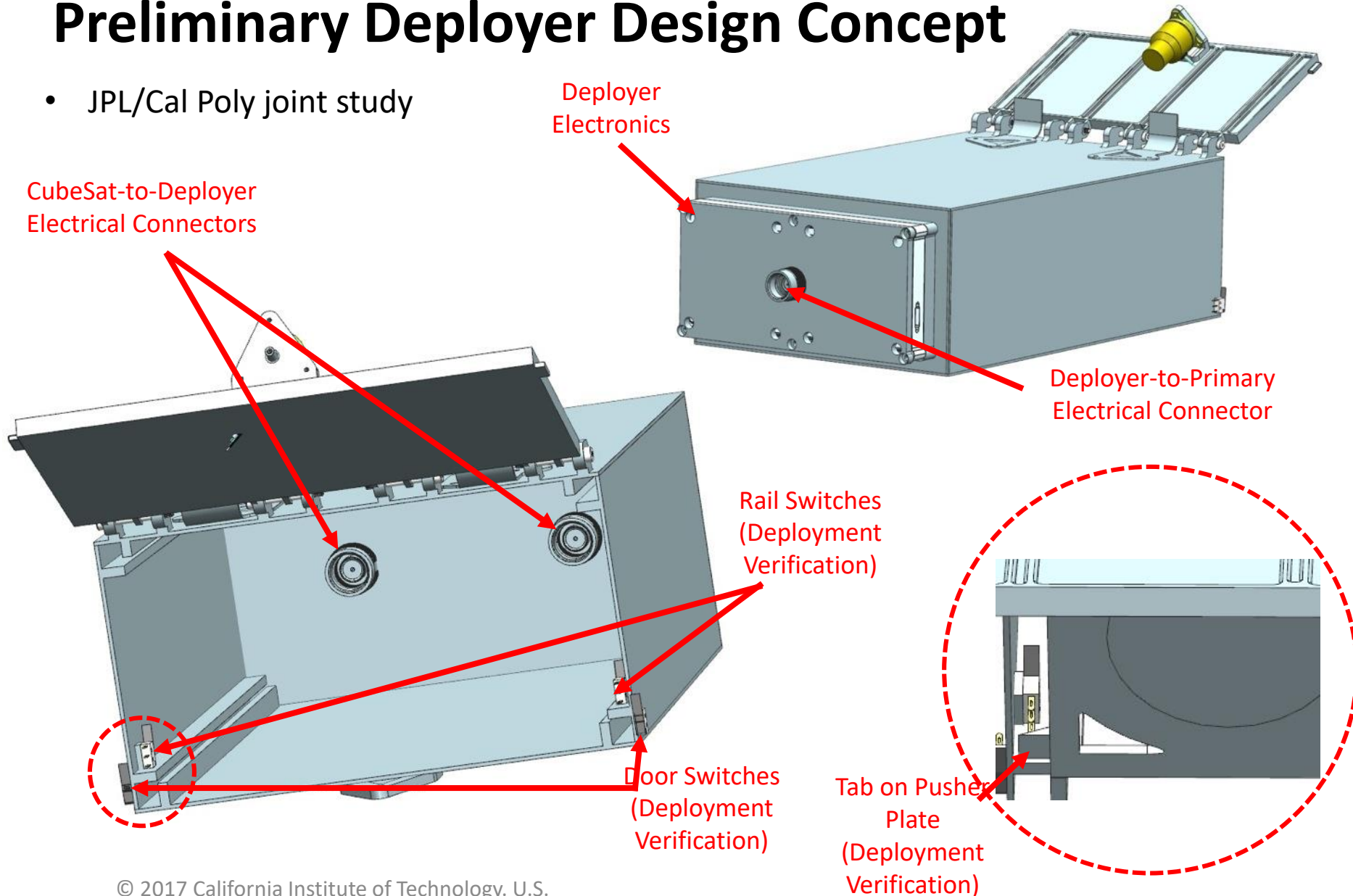
MarCo 28 dBi



# Deep Space Cubesat

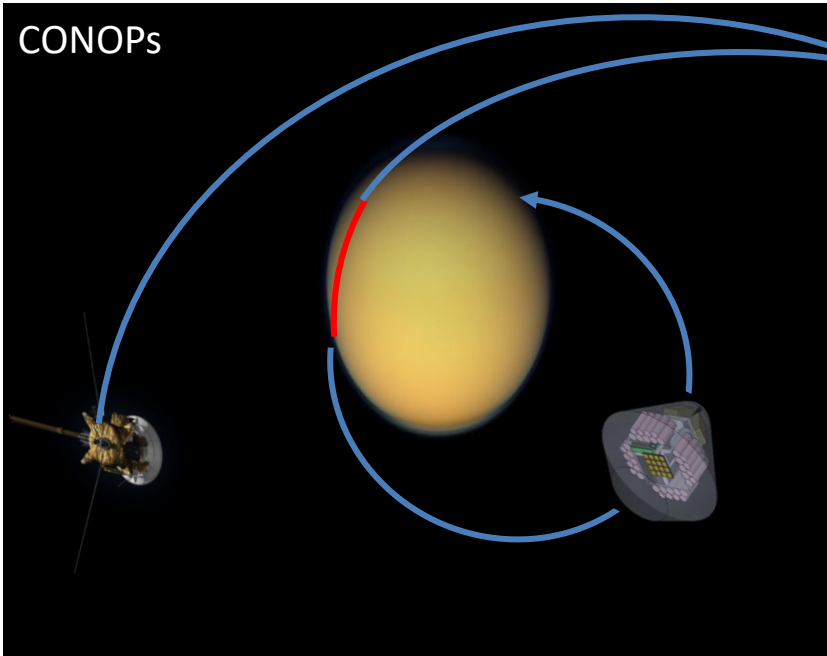
## Preliminary Deployer Design Concept

- JPL/Cal Poly joint study



# Titan Arrow Concept

CONOPs



## Mission Overview

- Primary S/C orbiting Saturn with flybys of Titan
- **Probe released from Primary onto spin stabilized "dive" trajectory**
  - Primary deflects from entry trajectory post separation
- Probe skims through the atmosphere down to homopause (~500 km)
  - Collects in situ samples for mass spec analysis
  - Probe performs aerocapture maneuver
- Probe exits atmosphere, drops backshell and transmits data to Primary to be sent to Earth
- Probe disposed to acceptable location on Titan on next periapse pass

## Science Overview

- Huygens Probe didn't sample upper atmosphere
- Upper atmosphere data desired for complete model

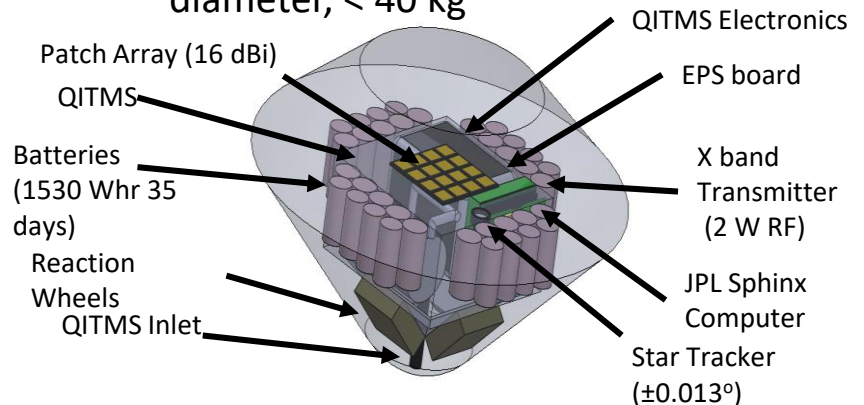
### Titan Arrow Objectives:

- Determine Upper atmosphere constituents (Ne, Ar, Kr, Xe)

Constituents determined with Quadrupole Ion Trap Mass Spectrometer (QITMS)

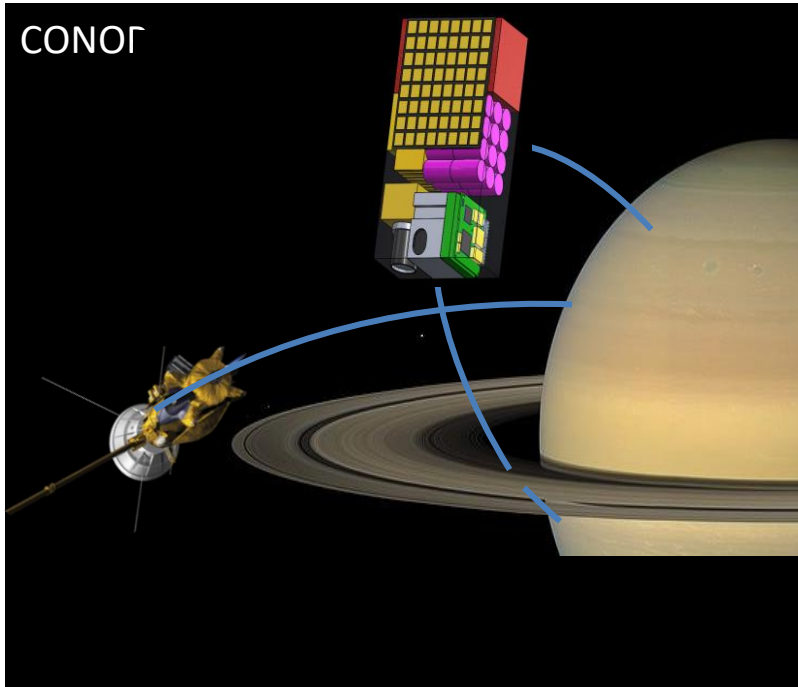
## Spacecraft Concept

- Galileo based 45° sphere cone, ~0.55 m diameter, < 40 kg





# Saturn Ring Diver Concept



## Mission Architecture

- 6U CubeSat rides along with primary mission to Saturn
- **Released at apoapse after Primary does Saturn orbit insertion**
- CubeSat performs inclination change maneuver  $\sim 45^\circ$
- CubeSat dives through narrow gap in rings while taking pictures
- If it survives, it transmits images to Primary via high gain antenna
- CubeSat continues in ring diving orbit if it survives, is destroyed by rings if it doesn't

## Science Overview

### Ring Science Gaps

- Mass, Age, Structure

Ring Diver investigates the ring structure by:

- Determine density of Saturn's ring (TBD)
- Size and distribution of ring particles
- Particle Morphology

Objectives achieved with <10 cm per pixel resolution camera

## Spacecraft Concept

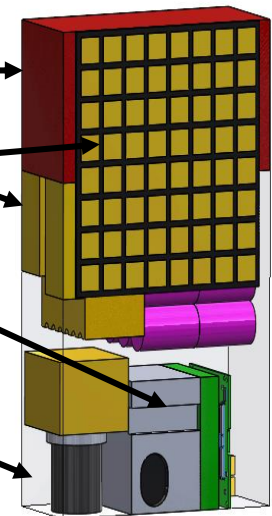
Aerojet Rocketdyne MPS120XW  
( $\sim 250$  m/s with AF-M315E)

IRIS Radio, 8x8 patch array  
(100 kbps @ 150,000 km)

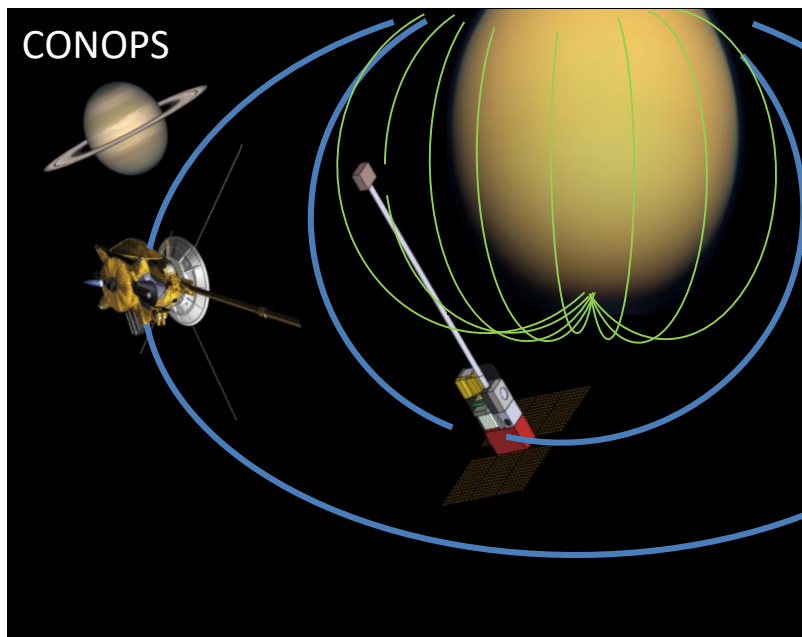
BCT XACT 50 ( $0.003^\circ$  accuracy)

JPL Intellicam  
(10cm/pixel at 800m)

Single RHU  $\sim 1$  W heat



# Investigating Titan's Magnetosphere



## Mission Overview

- Primary Spacecraft inserts into Titan orbit
- **6U CubeSat released into same orbit**
  - ~5.8 hour orbit
- Deploys magnetometer on 0.6m boom
- 5 orbits of 1 and 0.03 Hz measurements for the magnetometer and plasma instrument respectively
- 90 orbits recharging batteries and relaying to Primary via S/C low gain antennas
  - Primary relays data back to Earth
- Disposal into Titan

## Science Overview

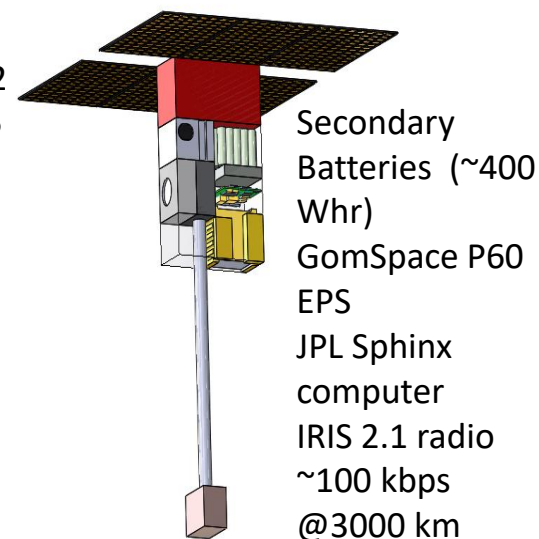
- Measure interaction of solar wind and Titan's magnetosphere
- Map Titan's magnetosphere

Objectives achieved with a Vector Helium magnetometer and Faraday Cup plasma instrument

## Spacecraft Concept

6 panel solar array (1.2 W)  
Aerojet Rocketdyne MPS12  
~250 m/s with AF-M315  
BCT XACT 50 (0.003°)  
JPL PlasMag  
(boom ~ 0.6m)

Single RHU ( ~1 W heat)



# Concepts for Surface Mobility Systems

Under the Ice

- Subsurface probes
- Drones on Titan or Mars



Through the Ice



Exploring Mars





COSPAR 2017

# Humanoid Robots

Kirobo on ISS

“That’s one small step for me”



# Humanoid Robots

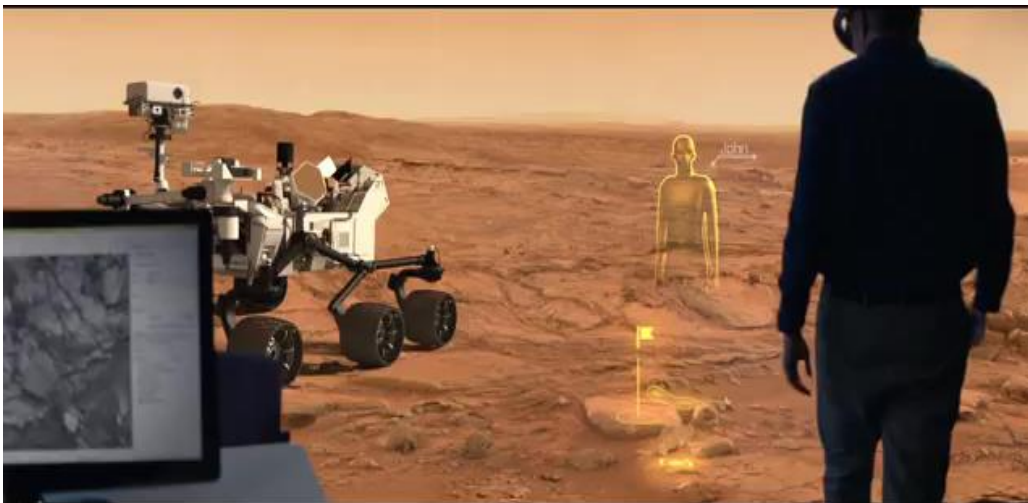
Artificial Intelligence?



Tool use - DARPA



Augmented Reality



Motion Capture



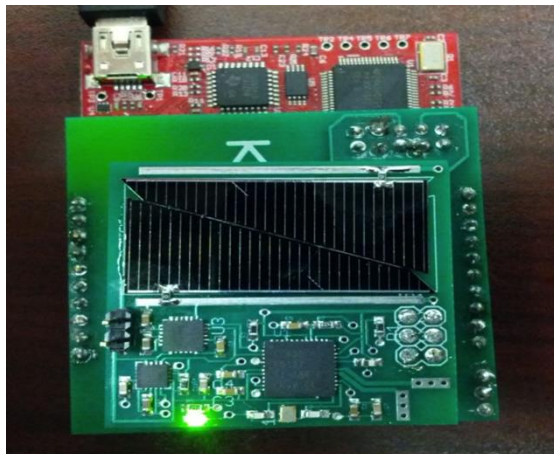
# Going Interstellar

Breakthrough Starshot

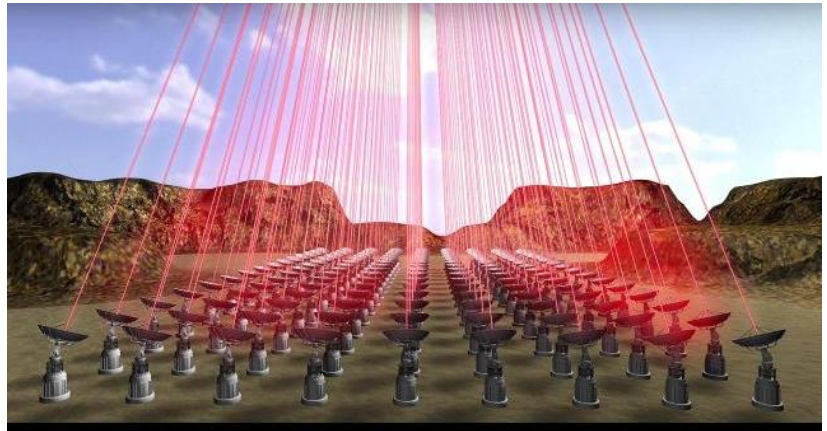


[breakthroughinitiatives.org/Initiative/3](http://breakthroughinitiatives.org/Initiative/3)

Kicksat Sprite



picosat (1-2 g)





# Summary

- The building blocks are lining up for some really exciting “Discovery-class” Smallsat missions in the very near future
- Miniaturization of instruments in particular has seen significant progress
- Smallsats allow fast-track infusion of technology for all future deep space missions
  - Don’t have to wait 40 years like we did for solar sails
- On Earth, some technologies – smaller instruments, AI, robotics, adv. manufacturing – are taking off exponentially
- When these exponential technologies converge and are space-adapted they will open up mind-blowing possibilities!